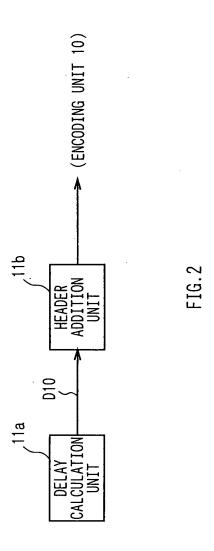


FIG. 1



٠
က
5
$\mathbf{H}$
ц.

0 2 4 6 8 10 12 1	10 112	10 112	10 112	10 112	10 112 11	112		4	14 16 18 20	8	20	22	24	22 24 26 28 30 32 34 36 38 40 42 44 46	78	99	32	34	36	38	40	42	44	46
100 B01 B02 B03 P04 B05 B06 B07	1 802 803	B03	$\sim$	P04 B05 B06 B	B05 B06 B	B06 B	18	10	108	809	B10	B11	P12	108 809 810 811 P12 813 814 815 P16	B14	815	P16				;			
100 P04 B01 B02 B03 I08 B05 B06 B07 P12 B09 B10 B11 P16 B14 B13 B15	_	_	_	P04 B01 B02 B0	B01 B02 B0	B02 B(	18	123	108	805	908	807	P12	B09	<b>B10</b>	B11	P16	B14	<b>B13</b>	815				
8 8 0 9	8	8	8	8	8		8		0	<sub>∞</sub>	<sub>∞</sub>	<sub>∞</sub>	0	8	8	8	0	9	10	8				
4 10 2 2 2	2 2	2 2	2 2	2 2	2 2		2		10	2	2	2	10 2		2	2	10	4	0	2				
100 B01 B02 B03 P04 B05 B06 B07 I08 B09 B10 B11 P12 B13 B14 B15	100 801 80	100 801 80	100 801 80	I00 B01 B0	100 801 80	B01 B0	8	2	B03	P04	<b>B05</b>	<b>B06</b>	807	108	809	B10	811	P12	<b>B13</b>	<b>B14</b>	815			

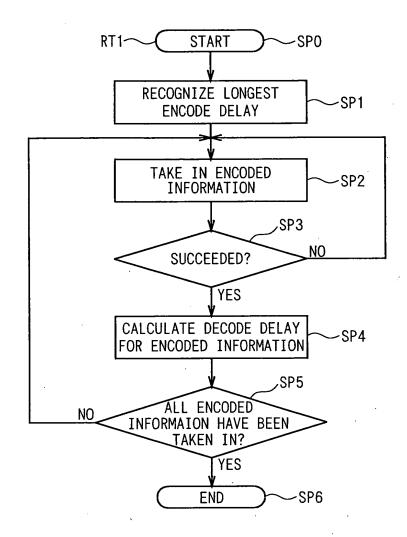


FIG.4

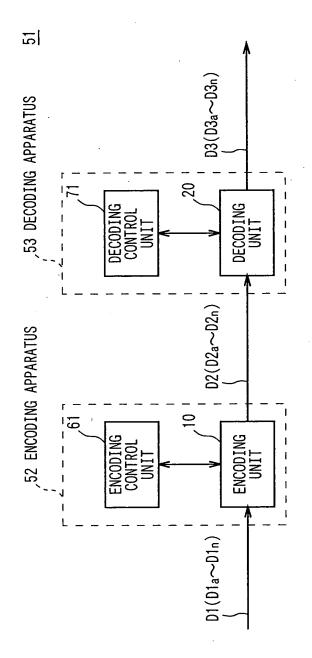


FIG. 5

44						P1(
42						<b>B15</b>
40						<b>B14</b>
38		B13	12	0	0	B13
36		<b>B14</b>	8	4	4	P12
34		815	4	8	&	P11 P12 B13
32	P16	P16	0	12	15	P10
30	815	<b>B</b> 12	9	9	. 9	P08 P09 P10 P10
28	814	P11	9	9	9	60d
26	<b>B13</b>	01d	9	9	4	P08
24	P12	60d	9	9	4	P07
22	P11	80d	9	9	4	P06
20	P10	P07	9	9	4	P04 P05 P05
. 18	60d	90 <i>d</i>	9	9	7	P05
16	80d	P05	9	9	2	P04
14	<b>L</b> 0d	P04	9	9	2	P03
12	P06	P03	9	. 9	2	P02
10	P05	P02	9	9	7	0 P01
8	P04	P01	9	9	2	100
9	P03	100	9	9	0	100
1	P02					
2	P01					
_0	001					

בוני פ

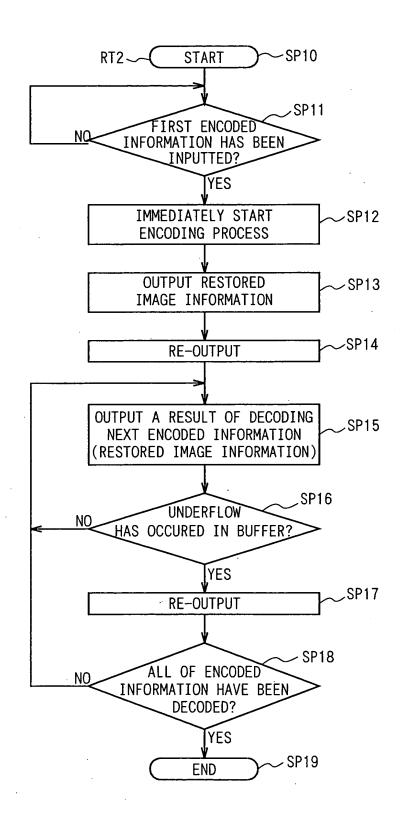
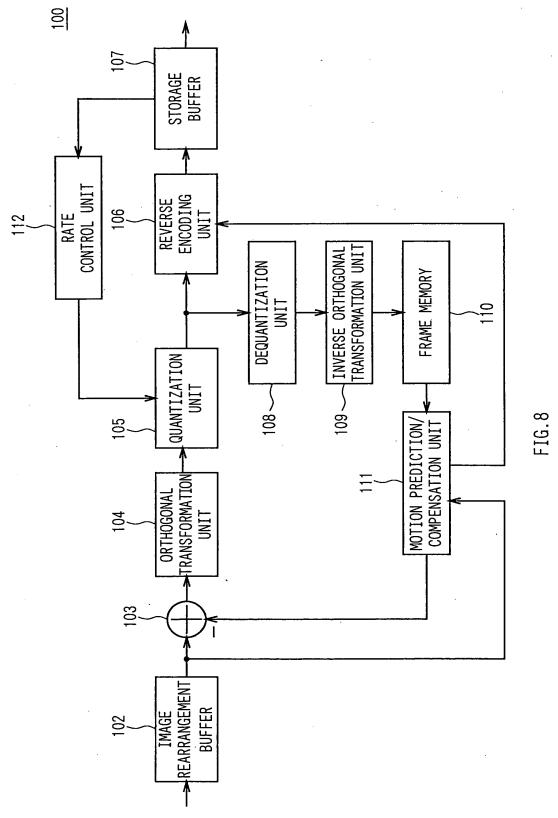
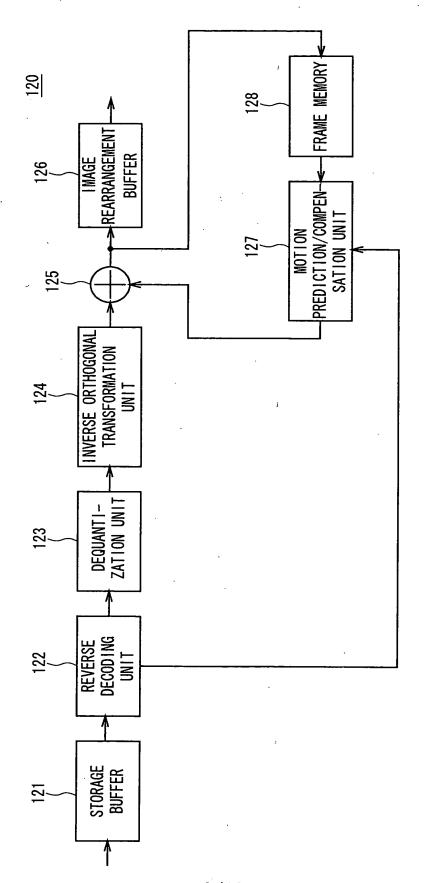


FIG.7





F1G. 9

## DESCRIPTION OF REFERENCE NUMERALS

1,51.....IMAGE REPRODUCTION SYSTEM, 2,52.....ENCODING APPARATUS, 3,53.....

DECODING APPARATUS, 10.....ENCODING UNIT, 11,61.....ENCODING CONTROL UNIT

11a.....DELAY CALCULATION UNIT, 11b.....HEADER ADDITION UNIT, 20.....

DECODING UNIT, 21,71.....DECODING CONTROL UNIT